



ARTHRON P

Climbing robotic platform with pods

BUDGET

€267K

GRANTS
OBTAINED

€181K

DGA RAPID FUNDING 2010 - 2011

THE PROJECT

The aim of the ARTHRON P project is to develop and demonstrate the wall-climbing abilities of a mobile inspection and exploration robot with a high crossing capability and moving on pods driven by a small number of motors. This work complements a first programme in the field of robots with poly-articulated structures.

ViaMéca
french mechanical cluster



PROJECT SPONSOR

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