



FAST

Fast Autonomous rover System

BUDGET	€1,600K
GRANTS OBTAINED	€853K
ANR FUNDING	2008 - 2011

THE PROJECT

The aim of this research project is to design an autonomous all-terrain terrestrial mobile robot capable of moving at very high speed (10 m/s). Its adaptability, both in mechanical and software terms, will enable it to maintain a high degree of precision in unknown environments whilst remaining stable and avoiding possible obstacles.

ViaMéca
French mechanical cluster



PROJECT SPONSOR

CEMAGREF

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