



# ROMANCE

Walking surveillance robot

BUDGET

€601K

GRANTS  
OBTAINED

€300K

AUVERGNE  
ERDF FUNDING

2011 - 2014

## THE PROJECT

The goal of this project is to develop a new infrastructure, sensitive site and private property surveillance robot.

The robot will automatically patrol a round programmed in advance by an operator. Along its route the robot will scan the surrounding area to detect and identify any intruder that may have entered the zone.

The project consists of combining a robot hardware platform with an artificial intelligence video surveillance solution in order to develop a new security surveillance product.

**ViaMéca**  
Pôle de compétitivité mécanique



## PROJECT SPONSOR

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